Km Shelly Chaudhary- CV

1. Name and full correspondence address:

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- 3. Institution: Meerut College Meerut, Uttar Pradesh, India.
- **4. Date of Birth:** 11/11/1996
- 5. Gender (M/F/T): Female

6. Academic Qualification

	Degree	Year	Subject	University/Institution	% of marks
1.	10 th	2012	Science, Maths, Hindi, English, SST, Drawing	U.P. Board, Uttar Pradesh	83.33%
2.	12 th	2014	Maths, Physics, Chemistry, English, Hindi	U.P. Board, Uttar Pradesh	88.80%
3.	B. Sc.	2014-17	Maths, Physics, Chemistry	CCS University, Meerut, Uttar Pradesh	82.80%
4.	M. A.	2017-19	Mathematics	CCS University, Meerut, Uttar Pradesh	79.60%
5.	M.Phil.	2019-2020	Mathematics	CCS University, Meerut, Uttar Pradesh	77.75%
6.	Ph. D.	2021- Present	Mathematics	National Institute of Technology, Kurukshetra	Pursuing (Part-time mode)

7. Qualified Exams

	Exam	Year	Subject	Institution/Agency
1.	JRF	2020	Mathematics	CSIR
2.	GATE	2019, 2021	Mathematics	IIT

8. Awards: Gold Medal in post-graduation from CCS University, Meerut



9. Work experience (in chronological order):

S.	Positions	Name of the	From	То	Pay Scale
No.	held	Institute			
1.		Department of Mathematics,	06/01/2023	Present	
	Professor	Meerut College, Meerut, Uttar			Grade Pay- 6000
		Pradesh-250001			(Basic Pay-57700/-)

10. Publications (List of papers published in SCI /SCIE/SCOPUS/UGC journals, in year wise descending order):

S.	Author(s)		Title		Name of Journal	Volume	Page	Year
No.								
1.	Km Shelly Chaudhary, Naveen Kumar	Fractional terminal control sch control manipulato	of	fast mode cacking robot	ISA Transections (Elsevier) (SCIE, SCOPUS) (IF:7.3)	142	57-69	(2023)

11. Accepted articles for publication in the International conferences

S.	Author(s)	Title	Name of	International/	Year
No.			Conference	National	
1.	Naveen Kumar, Km Shelly Chaudhary	Trajectory tracking control of Robot Manipulators using Fractional-order sliding manifold	International Conference on Systems, Control and Automation (Springer) (SCOPUS)	International	(2023)
2.	Naveen Kumar, Km Shelly Chaudhary	Motion control of underactuated cart-double-pendulum system via fractional order sliding mode controller	8th International Conference on Soft Computing: Theories and Applications (Springer) (SCOPUS)	International	(2023)

12. List of Journal for which Article Reviewed

S.	Name of Journal	Indexing	Publisher	Impact Factor	Year
No.					
1.	Ocean Engineering	SCI, SCIE, SCOPUS	ELSEVIER	5.1	(2023)

13. Papers presented in International/National Conference:

S.	Author(s)	Title	Name of Conference	International/	Year
No.				National	
1.	Naveen Kumar, Km Shelly Chaudhary	Trajectory tracking control of Robot Manipulators using Fractional-order sliding manifold	International Conference on Systems, Control and Automation (Springer) (SCOPUS)	International	(2023)
2.	Km Shelly Chaudhary, Naveen Kumar,	Fractional order sliding mode tracking control of nonholonomic constrained mobile robots using neural networks	6th International Conference on Mathematical Modelling, Applied Analysis and Computation (Springer) (SCOPUS)	International	(2023)
3.	Km Shelly Chaudhary, Naveen Kumar,	Adaptive fractional order sliding mode tracking control of nonholonomic mobile robots	3 rd International Conference on Nonlinear Applied Analysis & Optimization ICNAAO-2023 (Springer)	International	(2023)